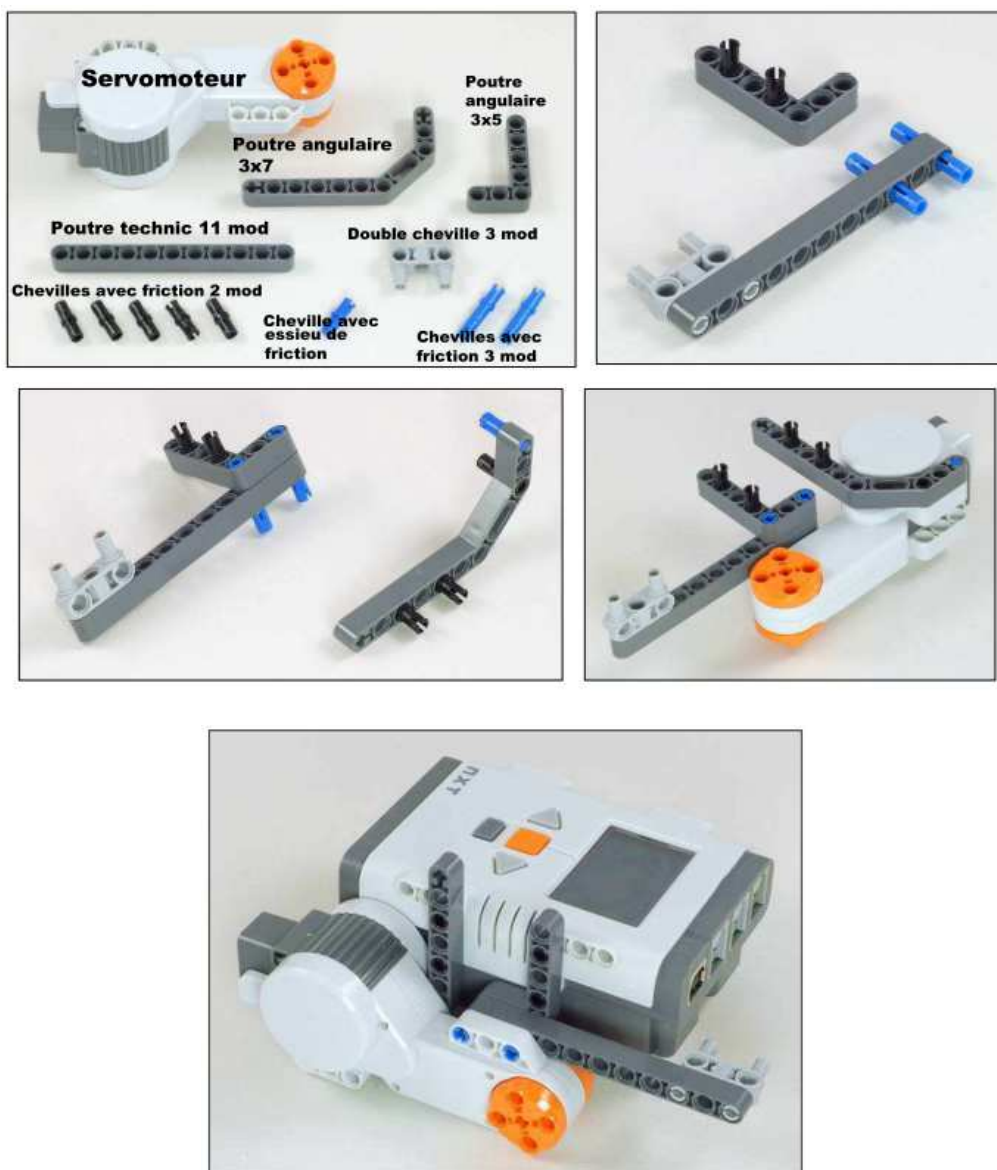


La robotique en FGA

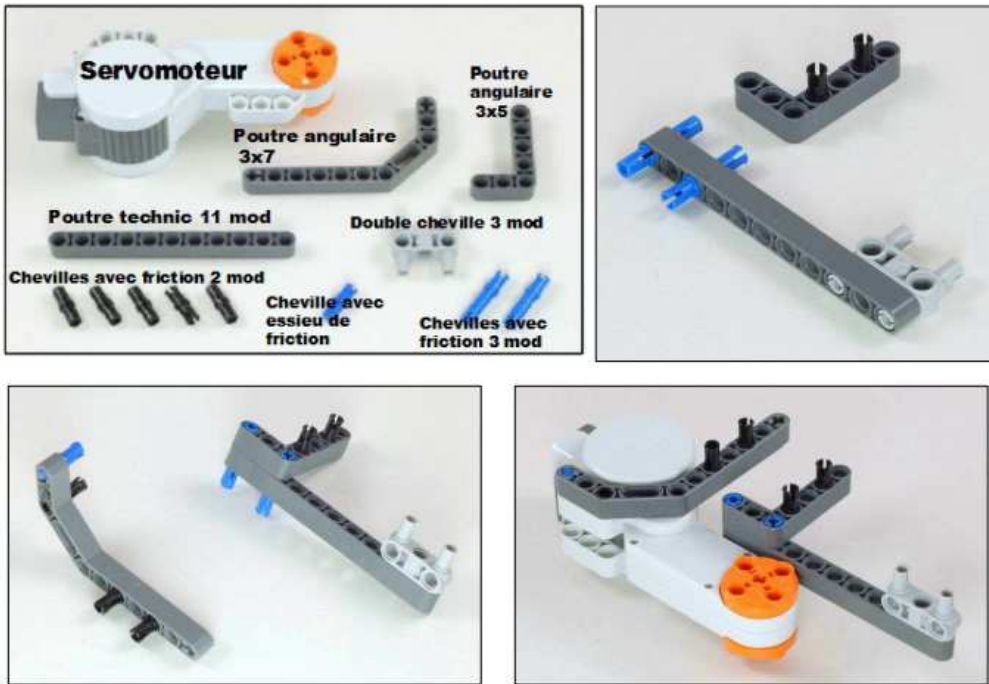
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Montage étape par étape

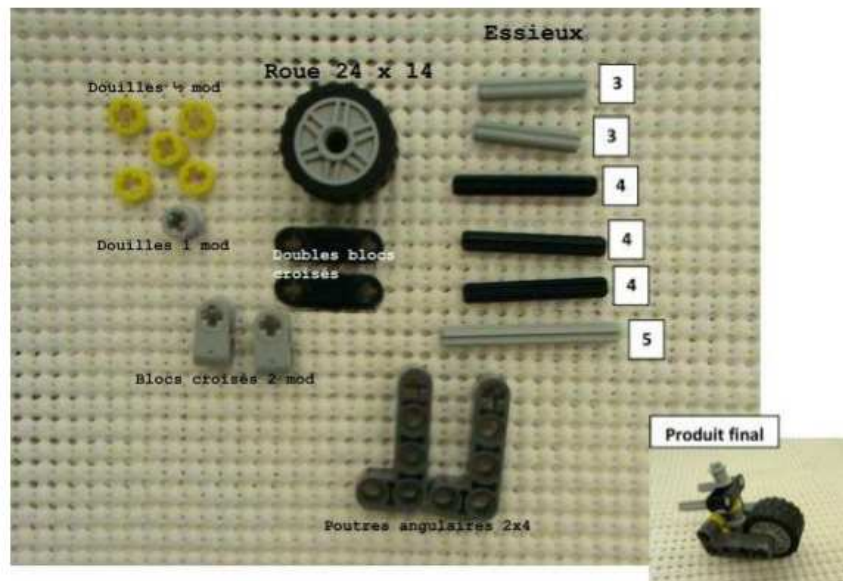
1. Côté droit

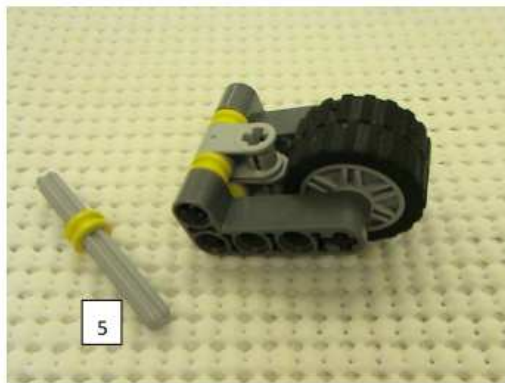
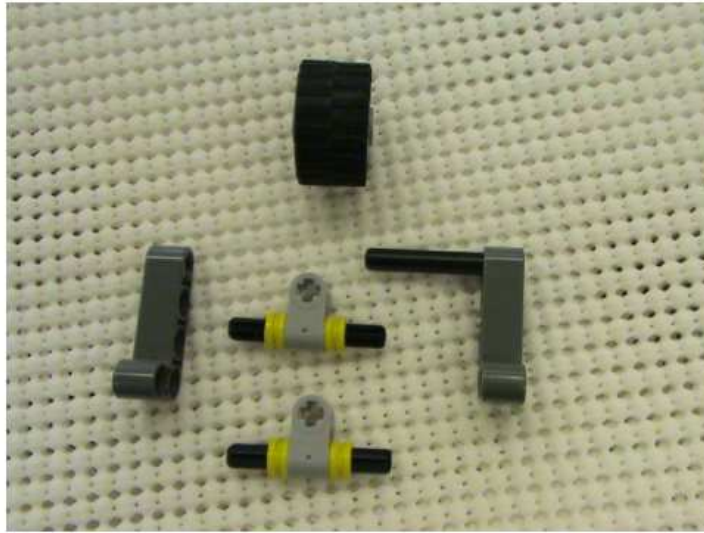


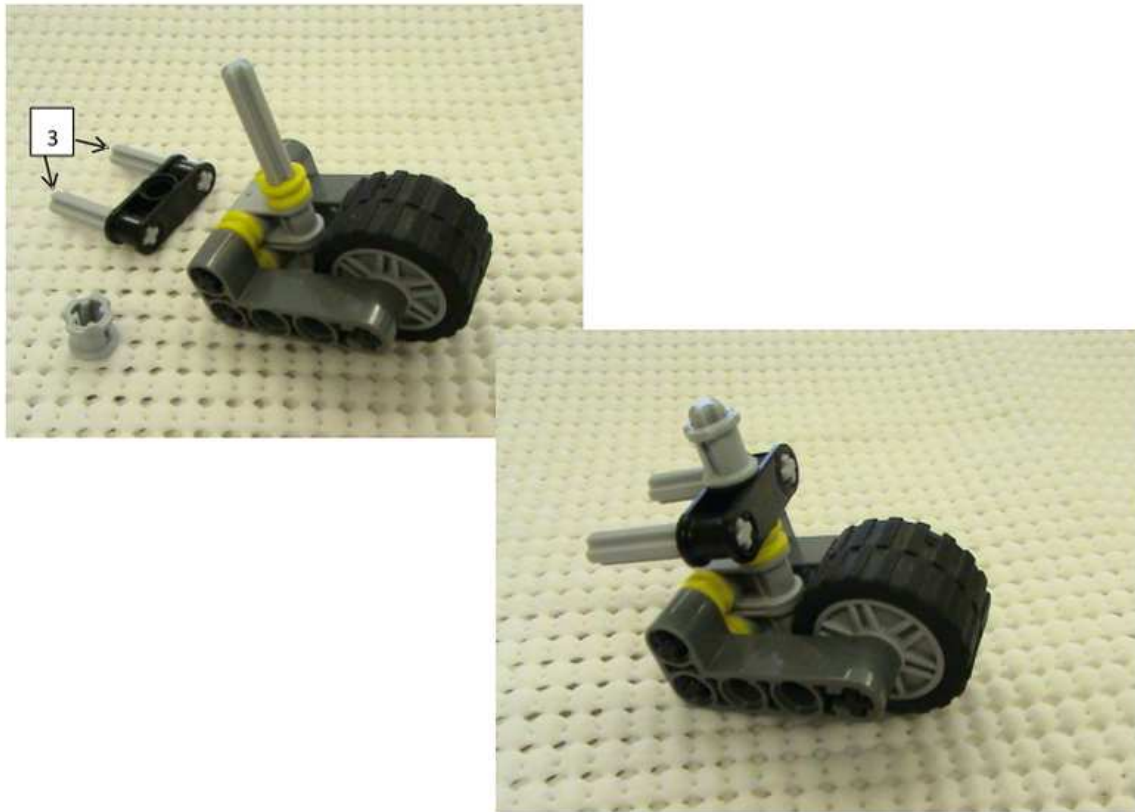
2. Côté gauche



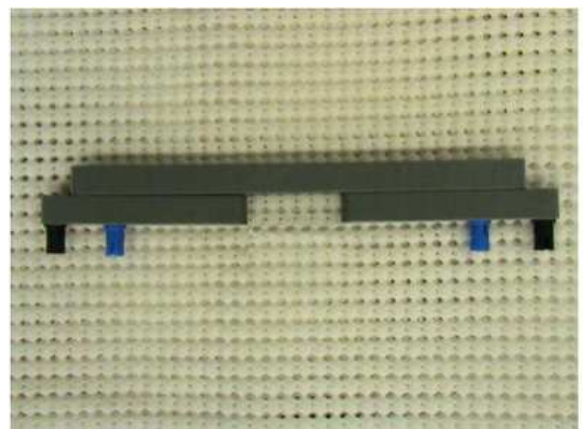
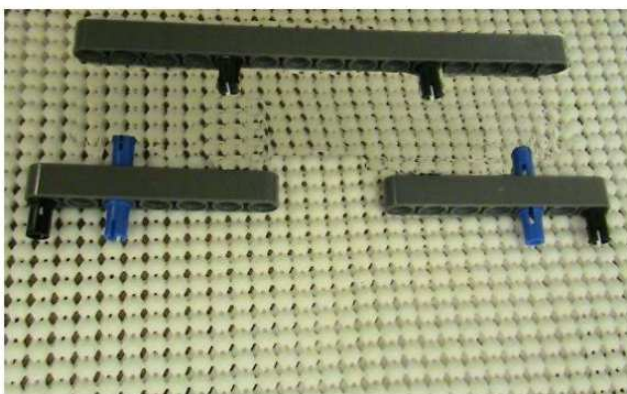
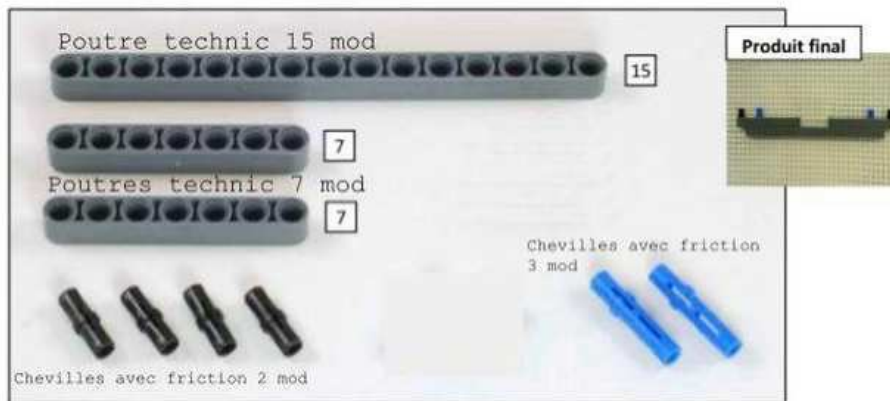
3. Roue pivotante

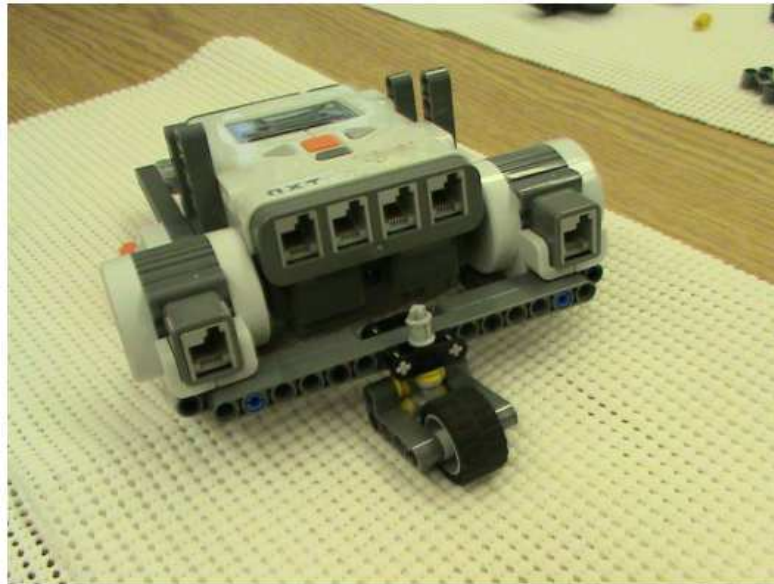
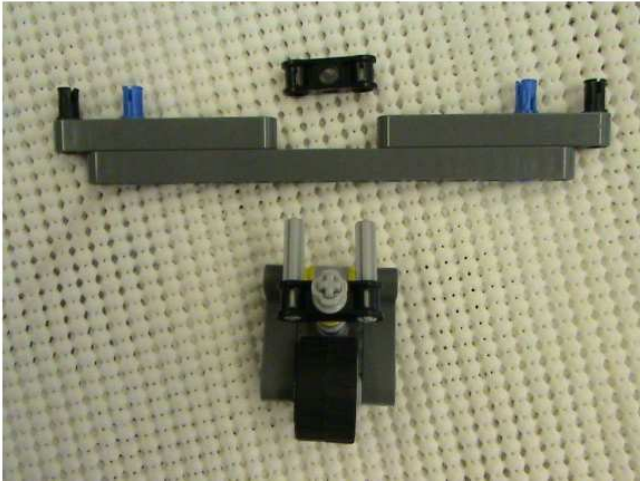




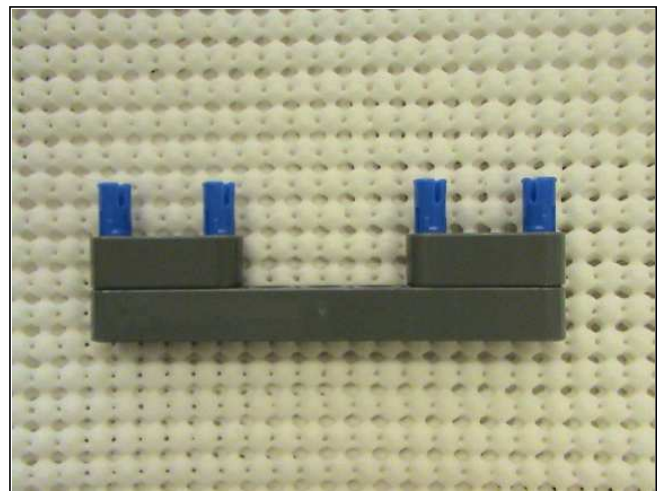
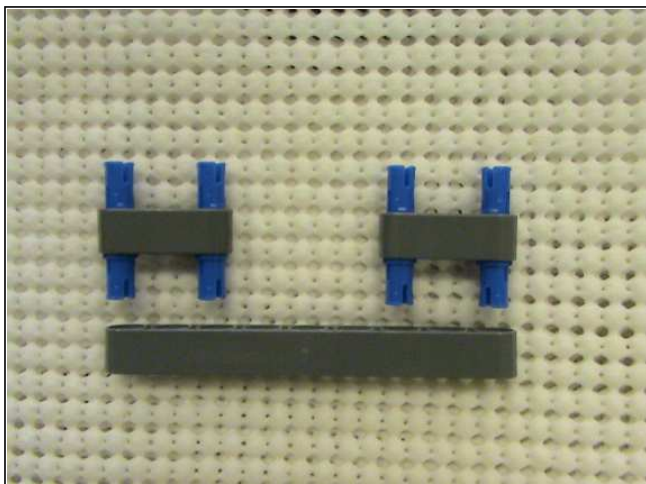
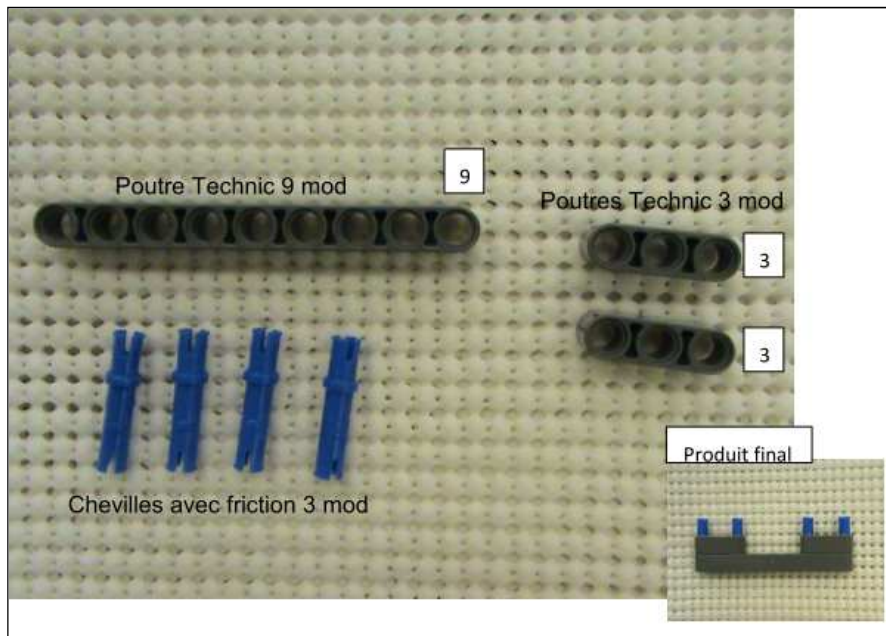


4. Arrière-train

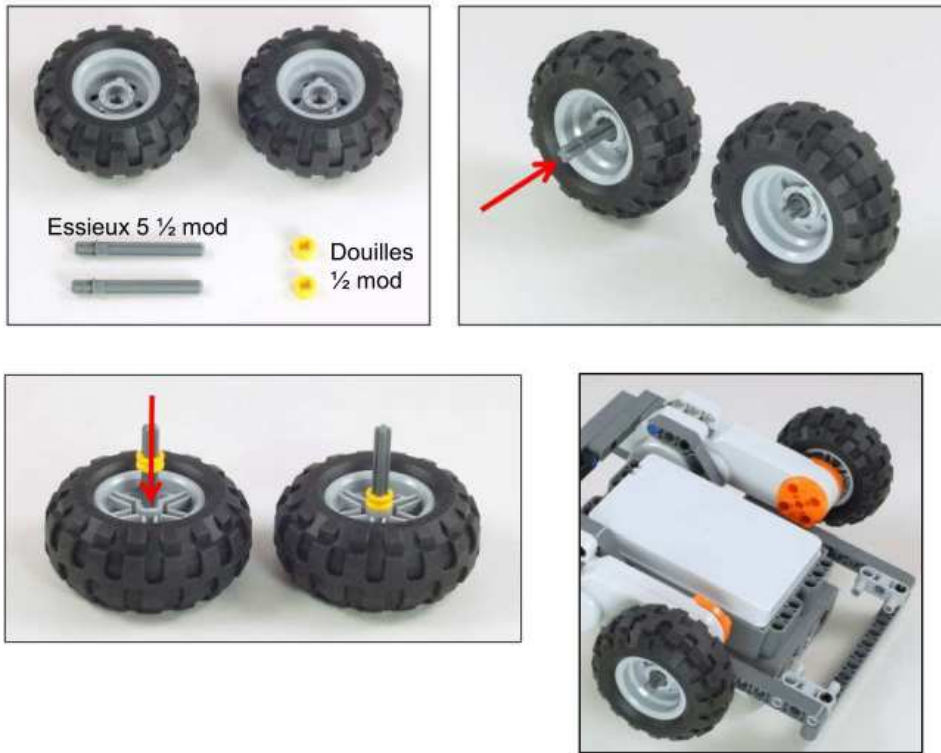




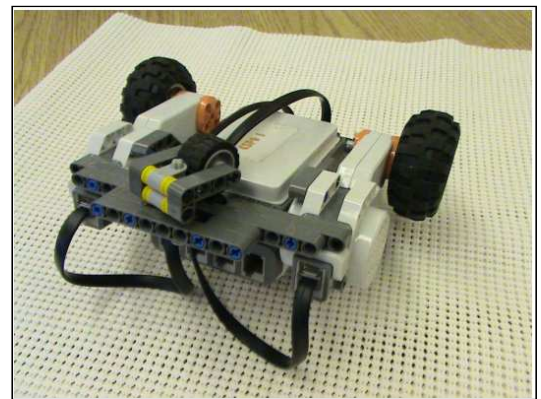
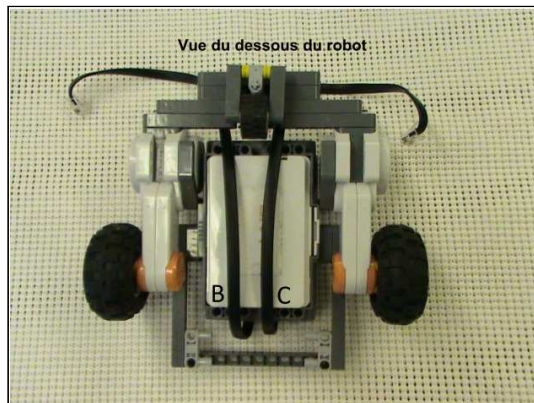
5. Pare-chocs arrière



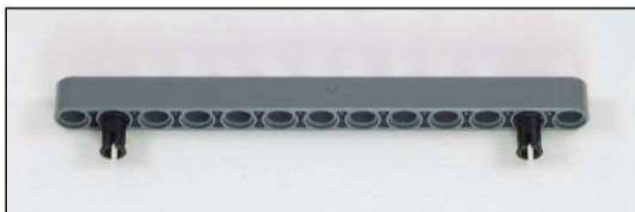
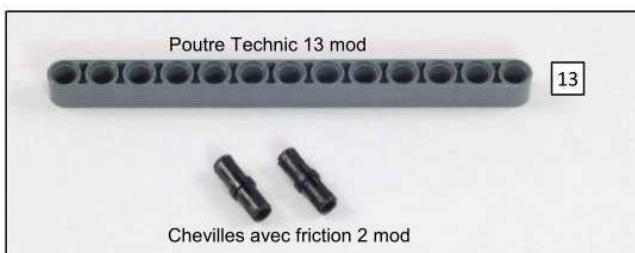
6. Roues



7. Fils aux moteurs

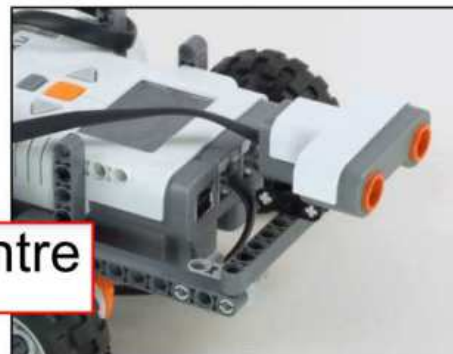


8. Pare-chocs avant

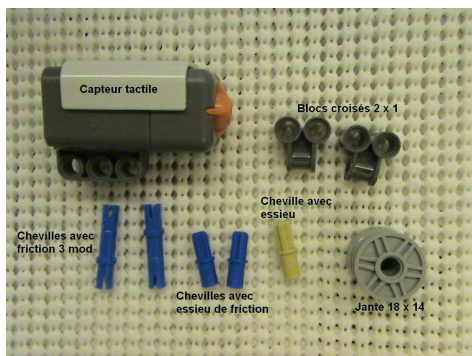


Les capteurs

1. Capteur ultrasons, à brancher dans le port 4

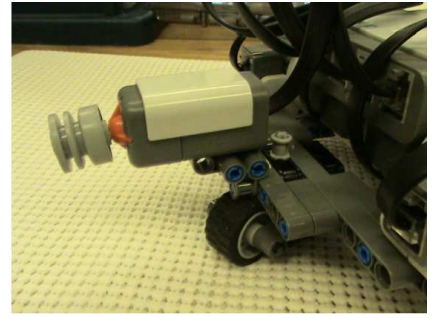
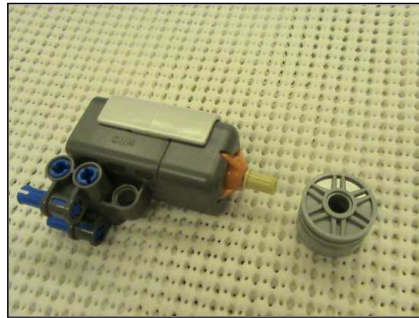
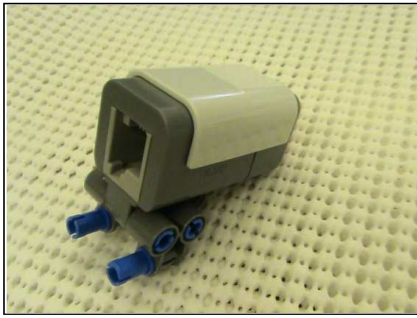


2. Capteur tactile, à brancher dans le port 1

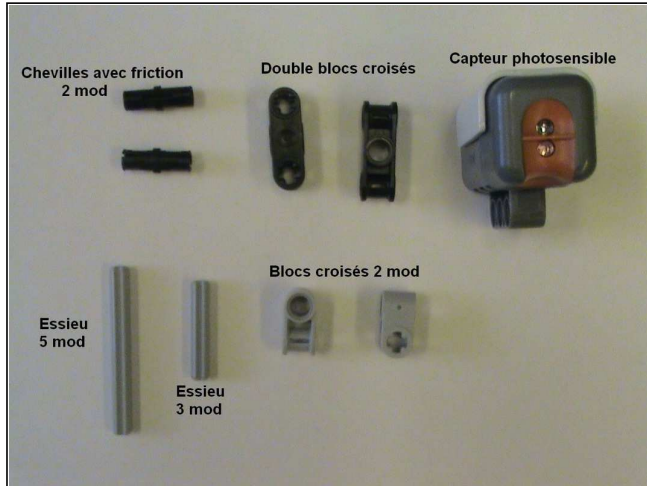


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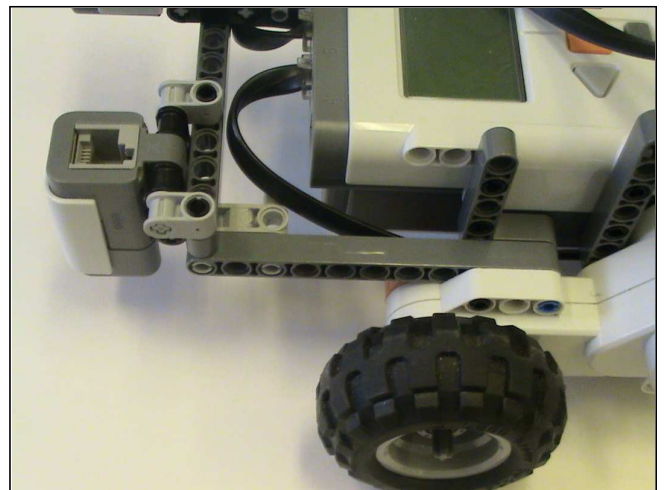




3. Capteur photosensible, à brancher dans le port 3



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